Practice class 5 – Shadows of polytopes

Aspects of linear algebra in Guillaume's research, at the intersection of discrete geometry, homotopy theory and higher category theory.

Q1. In this question, we will consider d linear transformations with domains and codomains as indicated:

$$\mathbb{R}^d \to \mathbb{R}^{d-1} \to \mathbb{R}^{d-2} \to \dots \to \mathbb{R} \to \{0\},\$$

where the jth arrow is given by the linear transformation

$$P^{(j)}:\mathbb{R}^{j}\longrightarrow\mathbb{R}^{j-1}$$

for $1 \leq j \leq d$ defined by

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{j-1} \\ x_j \end{bmatrix} \mapsto \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{j-1} \end{bmatrix}$$

For each of the following maps, compute its associated matrix, its mull-space, its column space, and verify the rank-nullity theorem.

- (i) the three maps $P^{(4)}$, $P^{(3)}$, and $P^{(2)}$
- (ii) the map $P^{(3)} \circ P^{(4)}$
- (iii) the map $P^{(2)} \circ P^{(3)} \circ P^{(4)}$.
- (iv) the maps $P^{(d)}$, for any natural number d.
- (v) the maps $P_j := P^{(j+1)} \circ \cdots \circ P^{(d-1)} \circ P^{(d)}$, for any $1 \le j \le d-1$.

Q2. Given *n* points $\mathbf{x}_1, \ldots, \mathbf{x}_n$ in \mathbb{R}^d , their *convex hull* is the set

$$\operatorname{Conv}(\mathbf{x}_1,\ldots,\mathbf{x}_n) := \{\alpha_1\mathbf{x}_1 + \cdots + \alpha_n\mathbf{x}_n \mid \forall i , \alpha_i \ge 0 \text{ and } \alpha_1 + \cdots + \alpha_n = 1\}.$$

A *polytope* is the convex hull of a finite set of points in \mathbb{R}^d for some *d*. *Polygons* (a triangle, a square, a pentagon,...) and *polyhedra* (a simplex, a cube, an octahedron,...) are examples of polytopes.

(a) Draw the *standard* 3-*simplex*

$$\Delta^3 := \operatorname{Conv}\left(\begin{bmatrix} 0\\0\\0 \end{bmatrix}, \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right) \subset \mathbb{R}^3.$$

(b) Compute the projections $P^{(3)}(\Delta^3) \subset \mathbb{R}^2$ and $(P^{(2)} \circ P^{(3)})(\Delta^3) \subset \mathbb{R}$, and draw the resulting polytopes.

The d-dimensional cyclic polytope on n vertices is the convex hull C(n, d) of the n points

$$\mathbf{x}_{j} := \begin{bmatrix} (j-1) \\ (j-1)^{2} \\ (j-1)^{3} \\ \vdots \\ (j-1)^{d} \end{bmatrix} \in \mathbb{R}^{d}$$

for $1 \leq j \leq n$.

- (c) Draw the cyclic polytopes C(3,2) and C(4,2). Hint: stretch the x axis.
- (d) Compute the projections $P^{(3)}(C(3,3))$ and $P^{(3)}(C(4,3))$, and draw the resulting polytopes. *Hint: projecting respects linear combinations.*
- (e) What is going on here? Make a conjecture.
- (f) Prove that conjecture.
- (g) [Challenge] Draw the cyclic polytopes C(3,3), C(4,3).

Q3. A hyperplane H in \mathbb{R}^d is the set of solutions to a single linear equation.

(a) For d = 1, 2, 3, what are hyperplanes geometrically?

Let $P := \text{Conv}(\mathbf{x}_1, \dots, \mathbf{x}_n) \subset \mathbb{R}^d$ be a *d*-dimensional polytope, and consider the intersection of P with an hyperplane H. Either we have

- (1) $H \cap P = \emptyset$,
- (2) H cuts P into 2 parts,

(3) $H \cap P \neq \emptyset$, and all the points on $P \setminus H$ lie on the same side of H.

The intersection $H \cap P$ of P with an hyperplane H is called a *facet* of P if

- $-H \cap P = \operatorname{Conv}(A)$ is the convex hull of a subset $A \subset \{\mathbf{x}_1, \ldots, \mathbf{x}_n\},\$
- $H \cap P$ satisfies condition (3) above, and
- the dimension of $H \cap P$ is one less than that of P.

Consider again the standard 3-simplex Δ^3 from Question 1. Its facets are all triangles.

- (b) How many facets does Δ^3 have?
- (c) Is the following convex hull a facet of Δ^3 ? Explain your answer.

$$\operatorname{Conv}\left(\begin{bmatrix}1\\0\\0\end{bmatrix},\begin{bmatrix}0\\1\\0\end{bmatrix}\right) \subset \mathbb{R}^3$$

In our class, we have not formally defined dimension yet. However, in the examples of the standard simplex and of cyclic polytopes C(n, d), the facets are exactly the convex hulls of *d*-element subsets satisfying (3) above.

More precisely, a *facet* of a cyclic polytope C(n,d) is the convex hull $\text{Conv}(\mathbf{x}_{i_1},\ldots,\mathbf{x}_{i_d})$ for a subset $I := \{i_1,\ldots,i_d\} \subset \{1,\ldots,n\}$ such that all points \mathbf{x}_j for $j \notin I$ lie on the same side of the hyperplane

$$H(I) := \{ \alpha_1 \mathbf{x}_{i_1} + \dots \alpha_d \mathbf{x}_{i_d} \mid \forall j \ , \alpha_j \in \mathbb{R} \text{ and } \alpha_1 + \dots + \alpha_d = 1 \}.$$

A facet of a d-dimensional polytope C(n, d) always has dimension d - 1.

- (d) Draw C(4,3), C(4,2) and C(4,1).
- (e) Compute the hyperplanes H(I) for the facets I of each of these three cyclic polytopes. You should obtain 4 equations of the form ax + by + cz = d for C(4,3), 4 equations of the form ax + by = c for C(4,2), and 2 equations of the form ax = b for C(4,1).

A facet I of C(n, d) is an *lower facet* (resp. *upper facet*) if all the points \mathbf{x}_j for $j \notin I$ are above (resp. below) the hyperplane H(I), with respect to the last (dth) coordinate. Let us denote by $\mathcal{U}(C(n, d))$ (resp. $\mathcal{L}(C(n, d))$) the set of upper (resp. lower) facets of C(n, d).

- (f) What are the upper and lower facets of C(4,3), C(4,2) and C(4,1)? Draw them in different colors.
- (g) What do you observe?
- (h) Draw $P^{(3)}(\mathcal{U}(C(4,3)))$ and $P^{(3)}(\mathcal{L}(C(4,3)))$, as well as $P^{(2)}(\mathcal{U}(C(3,2)))$ and $P^{(2)}(\mathcal{L}(C(3,2)))$.
- (i) What do you observe?
- **Q4.** [Challenge] We will now be interested in the cyclic simplex C(d + 1, d). Any subset $I \subset \{1, \ldots, d + 1\}$ of cardinality |I| = k + 1 defines, via the convex hull, a k-dimensional face $Conv(\{x_i\}_{i\in I})$ of C(d + 1, d). We define the k-source (resp. k-target) of C(d + 1, d) to be the set of k-faces F of C(d + 1, d) such that $P_{k+1}(F)$ belongs to $\mathcal{L}(P_{k+1}(C(d + 1, d)))$ (resp. $\mathcal{U}(P_{k+1}(C(d + 1, d))))$.

(i) Draw the k-source and k-target of C(4,3), for all $k \ge 0$.

We say that a sequence F_1, \ldots, F_ℓ of faces of C(d+1, d) is *k*-admissible if the *k*-target of F_i and the *k*-source of F_{i+1} have a *k*-face in common, for all $1 \le i \le \ell - 1$. We say that C(d+1, d)is *loop-free* if it does not admit any infinite *k*-admissible sequence, for any $k \ge 0$.

- (ii) Show that C(4,3) is loop-free. *Hint:* do a proof by exhaustion.
- **Q5**. [Challenge] A *tiling* of \mathbb{R}^2 a family \mathcal{F} of polygons such that
 - (a) $\bigcup_{F \in \mathcal{F}} F = \mathbb{R}^2$, and
 - (b) whenever two polygons $F, G \in \mathcal{F}$ intersect, their intersection $F \cap G$ is an edge of both.

Giving such a tiling, suppose moreover that for all polygons $F \in \mathcal{F}$, no edge of F is perpendicular to $\begin{bmatrix} 1\\ 0 \end{bmatrix}$. For each polygon $F \in \mathcal{F}$, the k-source and k-target of F for k = 0, 1 are defined in the same fashion as we did above for C(n, 2). Show that \mathcal{F} is loop-free.

If you want to know more about the connections with contemporary research topics, you can look at the following research articles/books (there are many pictures!):

- ▶ R.Street, *The algebra of oriented simplices*.
- ▶ M. Kapranov & V. Voevodsky, Pasting schemes and higher Bruhat orders.
- ▶ T. Dyckerhoff & M. Kapranov, *Higher Segal Spaces*.